

AN INTRODUCTION TO MAPLE FOR ECONOMICS 531

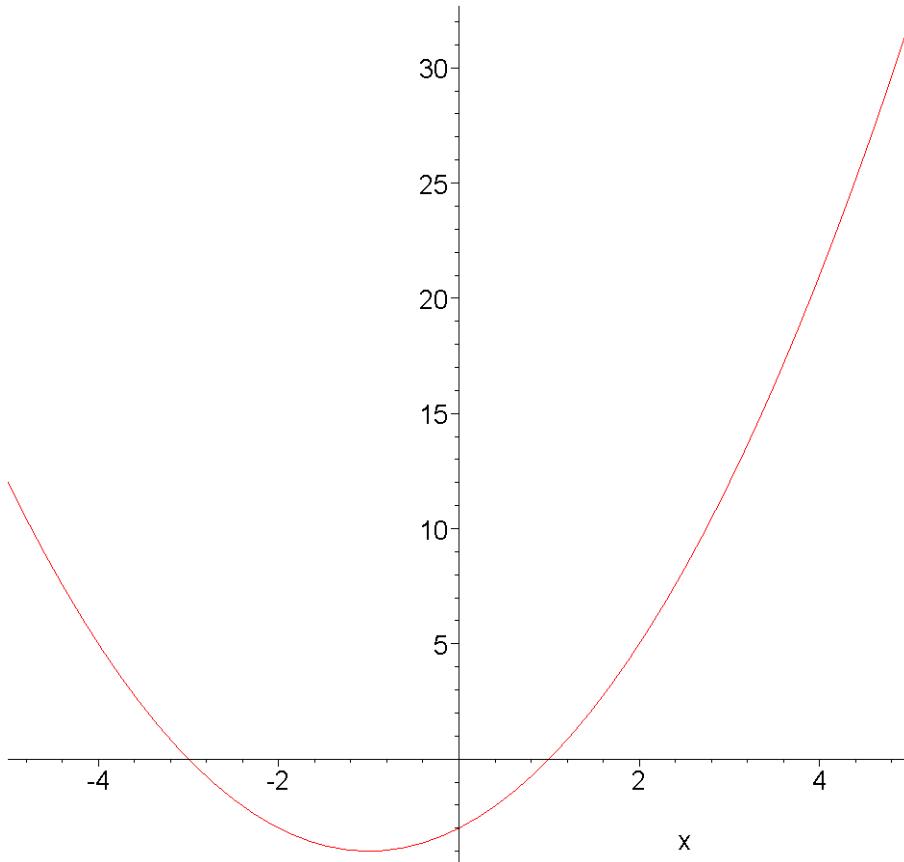
This file provides an introduction to some basic functions in Maple

1. Plotting in Two Dimensions

```
> restart:  
> with(plots):  
Warning, the name changecoords has been redefined
```

1.1 Basic Plot

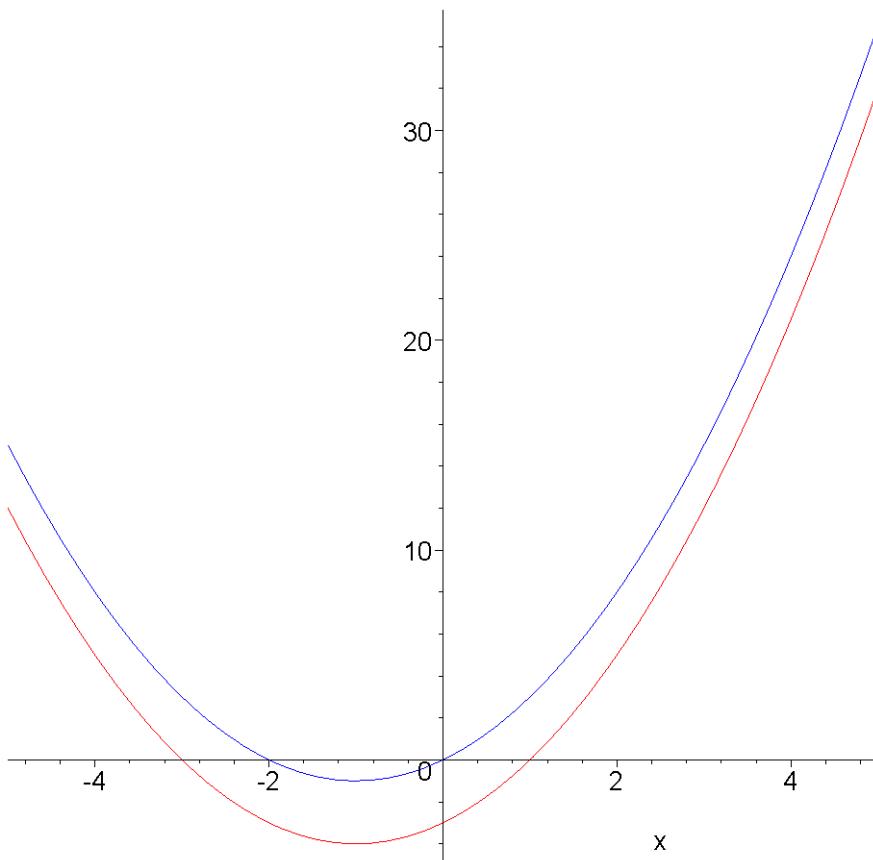
```
> f:=a*x^2+b*x-c;  
f := a x2 + b x - c  
> f1:=subs(a=1,b=2,c=3,f);  
f1 := x2 + 2 x - 3  
> plot(f1,x=-5..5);
```



1.2 Multiple Plot

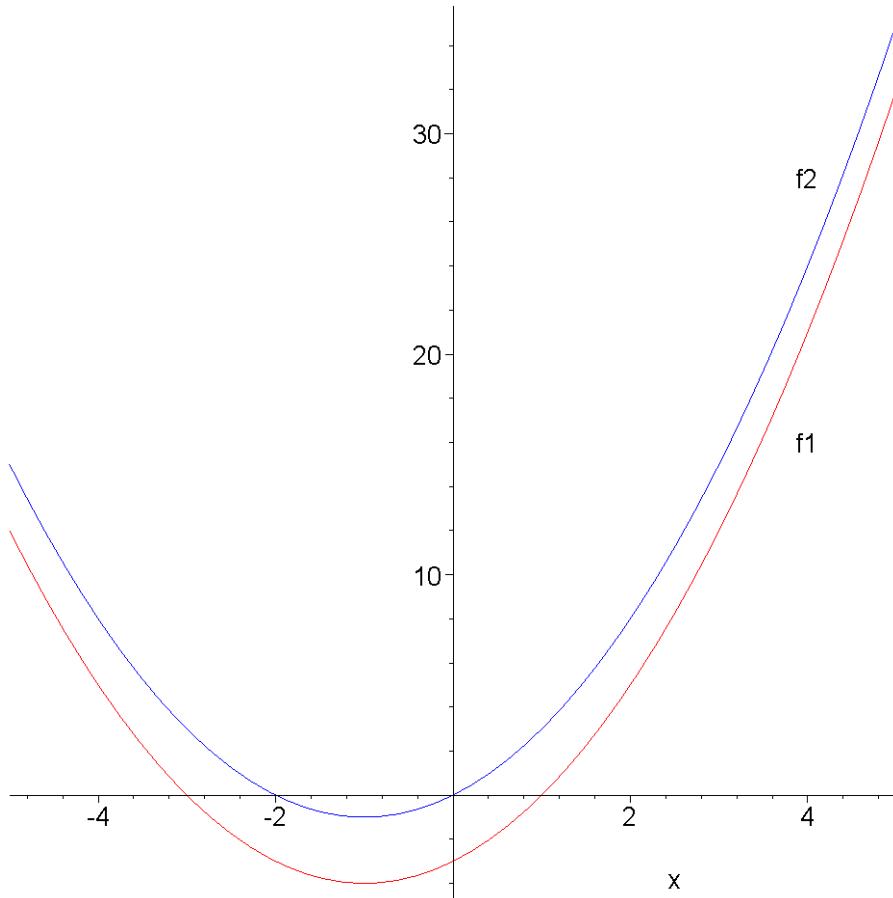
```
> f2:=subs(a=1,b=2,c=0,f);  
f2 := x2 + 2 x  
> g1:=plot(f1,x=-5..5,color=red):
```

```
[> g2:=plot(f2,x=-5..5,color=blue):  
> display(g1,g2);
```



1.3 Labeling the Plot

```
[> g3:=textplot([4,16,'f1']):  
> g4:=textplot([4,28,'f2']):  
> display(g1,g2,g3,g4);
```



1.4 Implicit Plots

A Constrained Optimization Example

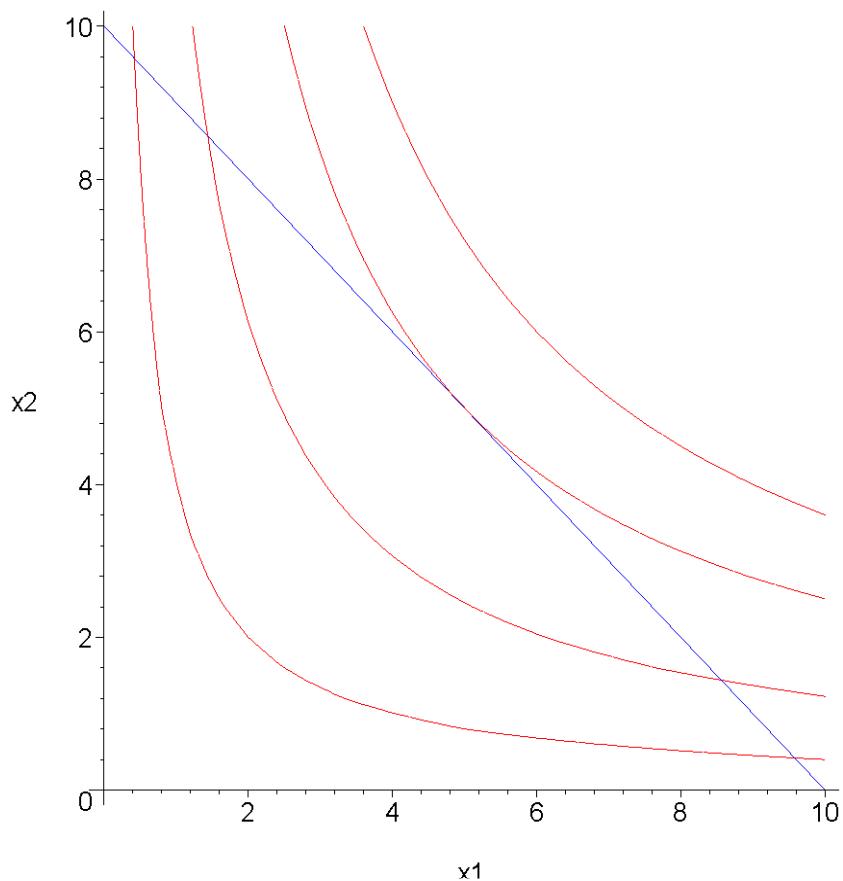
Cobb-Douglas Utility

```

> u:=x1^a*x2^b;
                                          $u := x_1^a x_2^b$ 
> a:=1/2;
> b:=1/2;
> p1:=1;
> p2:=1;
> m:=10;

> g1:=implicitplot(u=2,x1=0..10,x2=0..10);
> g2:=implicitplot(u=3.5,x1=0..10,x2=0..10);
> g3:=implicitplot(u=5,x1=0..10,x2=0..10);
> g4:=implicitplot(u=6,x1=0..10,x2=0..10);
> g5:=implicitplot(p1*x1+p2*x2=m,x1=0..10,x2=0..10,colour=blue):
> display(g1,g2,g3,g4,g5);

```

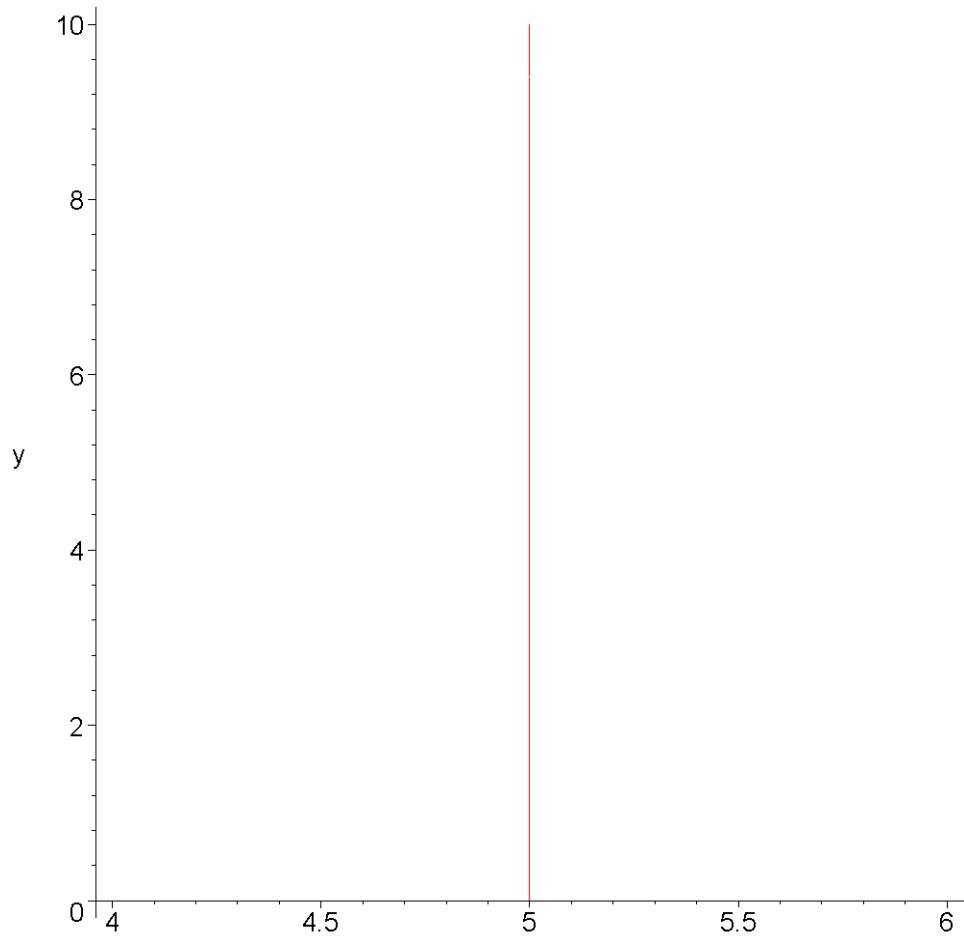


Resetting parameter values:

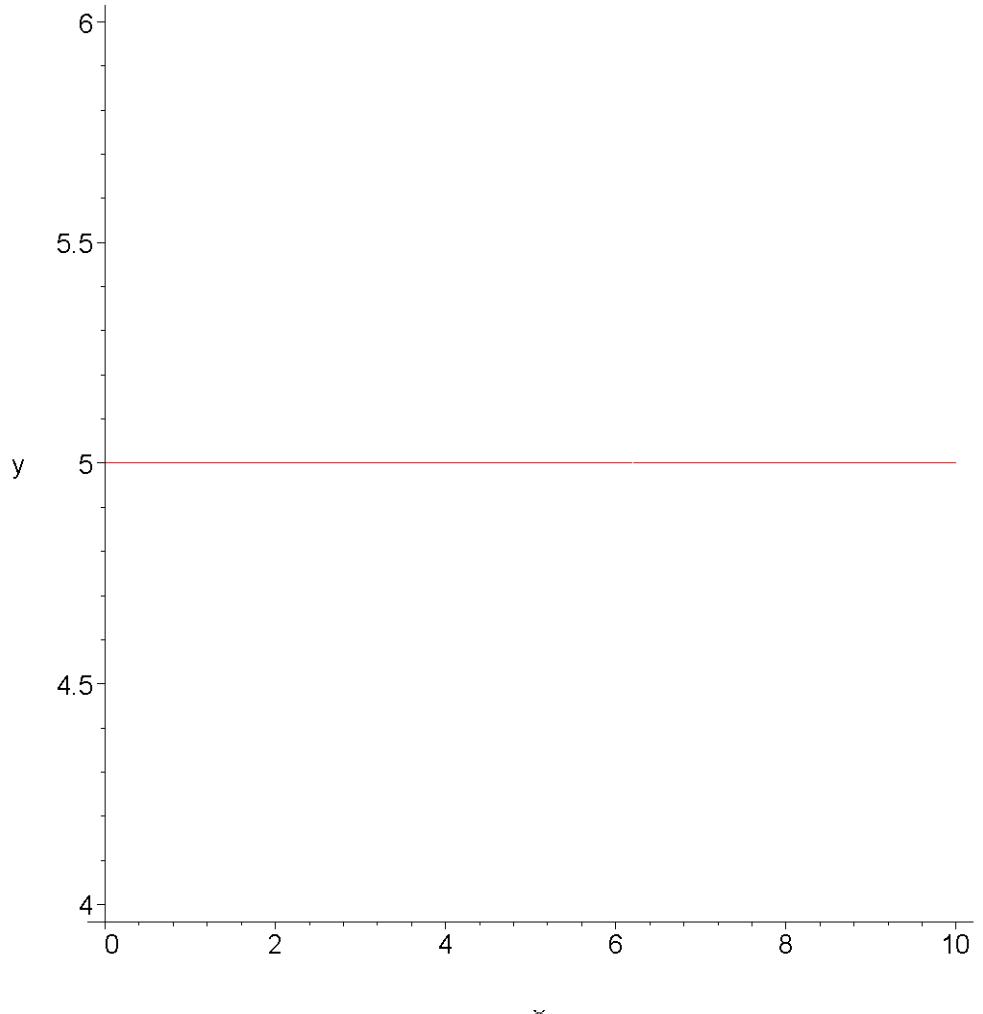
```
> a:='a':  
> b:='b':
```

1.5 Plotting a Constant

```
> g1:=implicitplot(x=5,x=0..10,y=0..10):  
> display(g1);
```

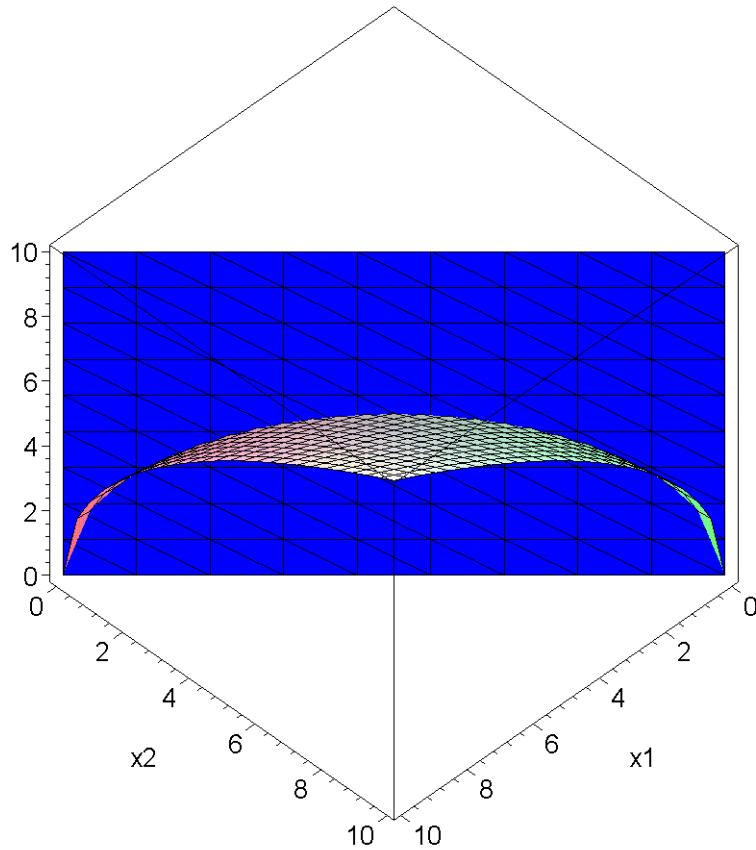


```
[> g1:=implicitplot(y=5,x=0..10,y=0..10):  
> display(g1);
```



2. Plotting in Three Dimensions

```
> u;
> a:=1/2;
> b:=1/2;
>
> g1:=plot3d(u,x1=0..10,x2=0..10,axes=boxed):
> g2:=implicitplot3d(p1*x1+p2*x2=m,x1=0..10,x2=0..10,y=0..10,axes=bo
  xed,colour=blue):
> display(g1,g2);
```



3. Solving Equations

> **restart:**

3.1 A Single Equation

> **f:=a*x^2+b*x-c;**

$$f := a x^2 + b x - c$$

> **eqn:=f=0:**

> **soln:=solve(eqn,x);**

$$soln := \frac{-b + \sqrt{b^2 + 4 a c}}{2 a}, \frac{-b - \sqrt{b^2 + 4 a c}}{2 a}$$

> **soln1:=soln[1];**

$$soln1 := \frac{-b + \sqrt{b^2 + 4 a c}}{2 a}$$

> **soln2:=soln[2];**

$$soln2 := \frac{-b - \sqrt{b^2 + 4 a c}}{2 a}$$

3.2 A System of Equations

A Constrained Optimization Example

```

> u:=x1^a*x2^b;
u :=  $x1^a x2^b$ 

> L:=u+lambda*(m-p1*x1-p2*x2);
L :=  $x1^a x2^b + \lambda (m - p1 x1 - p2 x2)$ 

> eqn1:=diff(L,x1)=0;
eqn1 :=  $\frac{x1^a a x2^b}{x1} - \lambda p1 = 0$ 

> eqn2:=diff(L,x2)=0;
eqn2 :=  $\frac{x1^a x2^b b}{x2} - \lambda p2 = 0$ 

> eqn3:=diff(L,lambda)=0;
eqn3 :=  $m - p1 x1 - p2 x2 = 0$ 

> soln:=solve({eqn1,eqn2,eqn3},{x1,x2,lambda});
soln :=  $\left\{ \lambda = \frac{e^{\left(\ln\left(\frac{m b}{p2 (a+b)}\right) b + \ln\left(\frac{m a}{(a+b) p1}\right) a\right)}}{(a+b)}, x1 = \frac{m a}{(a+b) p1}, x2 = \frac{m b}{p2 (a+b)} \right\}$ 

> x1hat:=subs(soln,x1);
x1hat :=  $\frac{m a}{(a+b) p1}$ 

> x2hat:=subs(soln,x2);
x2hat :=  $\frac{m b}{p2 (a+b)}$ 

> lambda_hat:=simplify(subs(soln,lambda));
lambda_hat :=  $\frac{\left(\frac{m b}{p2 (a+b)}\right)^b \left(\frac{m a}{(a+b) p1}\right)^a (a+b)}{m}$ 

```

The Maximum Value Function (The Indirect Utility Function)

```

> v:=subs(x1=x1hat,x2=x2hat,u);
v :=  $\left(\frac{m b}{p2 (a+b)}\right)^b \left(\frac{m a}{(a+b) p1}\right)^a$ 

```

The Lagrange Multiplier Again:

```
> simplify(diff(v,m));
```

$$\frac{\left(\frac{m b}{p2 (a+b)}\right)^b \left(\frac{m a}{(a+b) pI}\right)^a (a+b)}{m}$$

4. Integration

```
> F:=int(x2hat,p2);
```

$$F := \frac{m b \ln(p2)}{a + b}$$

```
> F:=int(x2hat,p2=1..2);
```

$$F := \frac{\ln(2) m b}{a + b}$$

```
>
```