

Sept 4, 2014

P423: Quantum Mechanics IILecture 1: Intro and review of the postulates of Quantum MechanicsELL160Prof: Rogério de SousaCourse website: [www.web.uvic.ca/~rdsousa/teaching/P423/Phys423.html](http://www.web.uvic.ca/~rdsousa/teaching/P423/Phys423.html)  
See syllabus and all online materials/rules.

▶ Homeworks and solutions posted online

→ A1 already posted, due Friday Sept 12 at 6pm in dropbox at the labwing  
(all assignments due Friday @ 6pm) (Labelled "P423").Office hours: Thursdays 3:00 - 4:00 pmTextbook: "Introduction to quantum mechanics", David J. Griffiths, 2<sup>nd</sup> Ed.Midterm exam: Oct. 9<sup>th</sup> in class

→ Take a photo of the class

2)

## Classical Mechanics

In Classical mechanics, the state of any physical system is determined by the position  $\vec{r} = (x, y, z)$  and velocity  $\vec{v} = \frac{d\vec{r}}{dt} = (\dot{x}, \dot{y}, \dot{z})$  of its points or particles.

We can introduce generalized coordinates  $q_i(t)$  and their velocities  $\dot{q}_i(t)$  to describe the system. Specifying  $q_i(t_0)$  and  $\dot{q}_i(t_0)$  at any given time  $t_0$  enables the calculation for all

times  $t$  of all future  $q_i(t)$  and  $\dot{q}_i(t)$ . For this we need is the Lagrangian  $L(q_i, \dot{q}_i)$ . The motion of the system is determined by the path that minimizes the action  $S = \int dt L \Rightarrow \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}_i} \right) = \frac{\partial L}{\partial q_i}$ . Define the Canonical momentum  $p_i$  as

$$p_i = \frac{\partial L}{\partial \dot{q}_i}$$

The  $q_i(t)$  and  $p_i(t)$  are called the fundamental dynamical variables. All physical

quantities associated to the system (observables, such as energy, angular momentum, etc)

can be expressed as a func of them. The <sup>total</sup> energy or Hamiltonian ~~is~~ given by

$$H(p_i, q_i, t) = \sum_i p_i \dot{q}_i - L,$$

and the motion of the system is determined by solving the Hamilton's eqns of motion (equivalent to Lagrangian)

$$\begin{cases} \dot{q}_i = \frac{\partial H}{\partial p_i} \\ \dot{p}_i = -\frac{\partial H}{\partial q_i} \end{cases}$$

For example, single particle in 3d:  $H = \frac{(\vec{p})^2}{2m} + V(\vec{q})$

$$\Rightarrow \begin{cases} \dot{\vec{q}} = \frac{\partial H}{\partial \vec{p}} = \frac{\vec{p}}{m} \\ \dot{\vec{p}} = -\frac{\partial H}{\partial \vec{q}} = -\frac{\partial V}{\partial \vec{q}} \end{cases}$$

Let us talk a bit more about the action  $S = \int_{t_i}^{t_f} L dt$ . Instead of fixing the endpoints  $Sq(t_f) = Sq(t_i) = 0$  let us allow the final endpoint to be arbitrary, so that we can think of  $S = S(q, t)$  when we made  $t_f \rightarrow t$ .

In that case:

$$\delta S = \int_{t_0}^t dt \left( \frac{\partial L}{\partial q} \delta q + \frac{\partial L}{\partial \dot{q}} \delta \dot{q} \right) = \frac{\partial L}{\partial \dot{q}} \delta q \Big|_{t_0}^t + \int_{t_0}^t dt \left( \frac{\partial L}{\partial q} - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) \right) \delta q$$

Poisson bracket in CM: For an observable  $A(q_i, p_i)$ :  
 $\frac{dA}{dt} = \{A, H\} + \frac{\partial A}{\partial t}$

Assume  $Sq(t_0) = 0$  but  $Sq(t)$  arbitrary:  $\delta S = p \delta q$   
Thus,  $\frac{\partial S}{\partial q_i} = p_i$ . Moreover,  $\frac{ds}{dt} = \frac{\partial S}{\partial t} + \sum_i \frac{\partial S}{\partial q_i} \dot{q}_i$   
so  $\frac{\partial S}{\partial t} = L - \sum_i p_i \dot{q}_i = -H$

$$\{A, B\} = \sum_i \left( \frac{\partial A}{\partial p_i} \frac{\partial B}{\partial q_i} - \frac{\partial A}{\partial q_i} \frac{\partial B}{\partial p_i} \right)$$

e.g.  $\{q_i, p_j\} = \delta_{ij}$

$$\Rightarrow \frac{\partial S}{\partial t} = -H$$

Therefore, summarizing CM:

- (i) The state of the system at any  $t$  is defined by specifying  $\vec{q}(t)$  and  $\vec{p}(t)$
- (ii) The value of all observables is completely defined at any  $t$  once the state is known.
- (iii) Time evolution uniquely determined for all  $t$  once the state at  $t_0$  is known

→ Deep philosophical consequence: Determinism, no free will! (Date joke - No matter what you will do, she will say no, or yes!)

This classical description is not correct. Particularly, it fails miserably at small energies and length scales. The formulation of QM answers the following questions:

- How is the state of a system described?
- Given that state, how can we predict the results of measurements of various physical quantities (observables)?
- How can the state of a system at arbitrary time  $t$  be found when the one at  $t_0$  is known?

## Postulates of Quantum Mechanics

I) At time  $t_0$ , the state of a system is defined by specifying a ket  $|\psi(t_0)\rangle$  belonging to the vector space  $\mathcal{E}$ .

► Superposition principle: Linear combinations such as  $|\psi\rangle = \alpha|\psi_1\rangle + \beta|\psi_2\rangle$  are allowed states.

$\xrightarrow{\text{Complex numbers.}}$

"Hot application": How about storing/processing information with "quantum bits" = qubits

like  $\alpha|0\rangle + \beta|1\rangle$  instead of the usual 0's and 1's? Quantum Computation is an active area of research that is making a big impact.

II) Every measurable physical quantity  $A$  is described by an operator  $\hat{A}$  acting on  $\mathcal{E}$ ; this operator is called an observable.

→ Note how different QM is from CM:

- States are vectors in an abstract linear algebra sense.
- Observables are operators acting on this space.

III) The only possible result of the measurement of a physical quantity  $A$  is one of the eigenvalues of the corresponding operator  $\hat{A}$ .

► Since all  $A$  is always real,  $\hat{A}$  is by definition Hermitian,  $\hat{A} = \hat{A}^\dagger$ .

If the spectrum of  $\hat{A}$  is discrete, the results that can be obtained by measuring  $A$  are quantized.

For the case of a discrete nondegenerate spectrum:

IV) When  $A$  is measured on a system in the normalized state  $|\psi\rangle$ , the probability  $P(a_m)$

of obtaining  $a_m$  is  $P(a_m) = |\langle \mu_m | \psi \rangle|^2$ , where  $|\mu_m\rangle$  is the normalized eigenvector of  $\hat{A}$  associated with the eigenvalue  $a_m$ ,  $\hat{A}|\mu_m\rangle = a_m|\mu_m\rangle$ .

For discrete degenerate:  $P(a_m) = \sum_{i=1}^{g_m} |\langle \mu_m^i | \psi \rangle|^2$  where  $\{|\mu_m^i\rangle, i=1, \dots, g_m\}$

forms a basis of the space  $\hat{A}|\psi\rangle = a_m|\psi\rangle$

For continuous spectrum  $\hat{A}|\mu_\alpha\rangle = \alpha|\mu_\alpha\rangle$ , the probability of measuring  $\alpha \in [\alpha, \alpha+d\alpha]$

is  $|\langle \mu_\alpha | \psi \rangle|^2 d\alpha$   
Prob. density.

Example: Consider a basis for localized particles in 3d  $\{|\vec{r}\rangle\}$ . The quantity

$\psi(\vec{r}) = \langle \vec{r} | \psi \rangle$  is called "wavefunc" and

gives a "coordinate representation" of any state  $|\psi\rangle$  that basis  $\{|\vec{r}\rangle\}$ . Quantum particles are described by the matterwave  $\psi(\vec{r})$ ,

and the probability of measuring a particle localized at  $\vec{r}$  (i.e. at the state  $|\vec{r}\rangle$ ) is

$$|\langle \vec{r} | \psi \rangle|^2 = |\psi(\vec{r})|^2.$$

V) If the measurement of  $A$  in the system state  $|\psi\rangle$  gives the result  $a_m$ , the state of the

system immediately after the measurement is the normalized projection of  $|\psi\rangle$  onto the subspace associated with  $a_m$ :  $|\psi\rangle \xrightarrow{\text{measurement outcome } a_m} \frac{\hat{P}_m |\psi\rangle}{\sqrt{\langle \psi | \hat{P}_m | \psi \rangle}}$  where  $\hat{P}_m = \sum |\mu_m\rangle \langle \mu_m|$  for nondegenerate discrete spectra.



Now opening a parenthesis much slower than  $S(\hbar)$ :

$$\frac{\partial \Psi_{\text{class}}}{\partial t} \approx \frac{i}{\hbar} \underbrace{\frac{\partial S}{\partial t}}_{=-H} \Psi_{\text{class}} = \frac{1}{i\hbar} H \Psi_{\text{class}}$$

VI) The time evolution of the state vector  $|\Psi(t)\rangle$  is governed by the Schrödinger eqn

$$i\hbar \frac{\partial |\Psi(t)\rangle}{\partial t} = \hat{H} |\Psi(t)\rangle, \text{ where } H \text{ is the Hamiltonian func in operator form.}$$

But how to represent momentum? Use  $\vec{p} = \frac{\partial S}{\partial \vec{q}} = \vec{\nabla}_q S$ :

$$\vec{p} \Psi_{\text{class}} = (\vec{\nabla}_q S) \Psi_{\text{class}} = \frac{\hbar}{i} \left( \frac{i}{\hbar} \vec{\nabla}_q S \right) \Psi_{\text{class}} = \left( \frac{\hbar}{i} \vec{\nabla}_q \right) \Psi_{\text{class}}$$

the canonical momentum  $\vec{p} = \frac{\partial L}{\partial \dot{q}} \rightarrow \vec{p} = \frac{\hbar}{i} \vec{\nabla}_q$  in the "coordinate representation". In particular, the eigenstates of very important!

momentum are  $\Psi_{\vec{p}}(\vec{r}) \propto e^{\frac{i}{\hbar} \vec{p} \cdot \vec{r}}$ , and the wave func in momentum space is

$$\varphi(\vec{p}, t) = \frac{1}{(2\pi\hbar)^{3/2}} \int d^3r \Psi(\vec{r}, t) e^{-\frac{i}{\hbar} \vec{p} \cdot \vec{r}}, \text{ or in } d=1$$

$$\varphi(p, t) = \frac{1}{\sqrt{2\pi\hbar}} \int dx \Psi(x, t) e^{-\frac{i}{\hbar} p x},$$

with  $|\varphi(p, t)|^2$  the probability density for measurement of momentum.

One final comment about the quantum to classical correspondence: Because the commutator  $[x, p] = xp - px = i\hbar$  and the Poisson bracket  $\{x, p\} = 1$  we have

$$\{, \}_{\text{class.}} \rightarrow \frac{1}{i\hbar} [, ]_{\text{quantum}}$$